## LAB 1 - Talking Points

The intent of this spreadsheet is to provide some thoughts as to the sequence of operation required.

Although some PLC Programs have been sucessful in using Step Sequencers, Condition and Event Driven logic determines what Action will take place for this LAB.

Students need to be able to think through the process and determine what actions are simultaneious and which motions are interdependant.

There should be discussion regarding the lack of Inputs making deterministic evaluation difficult. Example: How can the position of X & Z Axis be determined without direct sensing?

Only the most critical Internal PLC Conditions are spelled out here (such as the TMR for Part in Place and Gantry Position Status)

Lids Conveyor			Pick and Place				Bases Conveyor			
Input State	s Action / Output	Status	Input	Status	Action / Output	Status	Input	Status	Action / Output	Status
E-Stop OFF			-				-			
Stop OFF										
Auto SS ON										
Start PB ON										
	In Cycle	ON								
	Clamp	OFF							Clamp	OFF
	Raise Positioner	OFF							Raise Positioner	OFF
					Advance X	OFF				
					Lower Z	OFF		r		
	Conveyor	ON							Conveyor	ON
	Emitter	Forced ON							Emitter	Forced ON
Detect Part ON		2					Detect Part	ON		
D. I. DI. TIAD DON	Part in Place TMR	ON					D. I. Dl. TMD	DONE	Part in Place TMR	ON
Part in Place TMR DON		OFF					Part in Place TMR	DONE	C	OFF
	Clares	OFF ON							Claren	OFF ON
	Clamp	UN		İ	Lower Z	ON		ļ	Clamp	ON
			Part Detected	ON	LOWEI Z	ON				
			rait Detected	ON	Grab	ON				
	Clamp	OFF			Lower Z	OFF				
	Clamp	0.1	** Z - Raised	ON	LOWE! L	011				
					Advance X	ON				
			** X - Advanced	ON		-				
					Lower Z	ON				
			** Z - Lowered	ON						
					Grab	OFF			Clamp	OFF
					Lower Z	OFF			Raise Positioner	ON
	Conveyor	ON		•					Conveyor	ON
							Part Exit	ON		
							Part Exit	OFF		
				i					Counter	+ 1
	** CLEAR	ON			** CLEAR	ON			** CLEAR	ON