Name: ______

Date:

Year Month Day

Assembler LAB 2 – Purposes: The student will learn to:

- **1.** Edit an existing Scene in Factoryio to create a unique layout with a new Pushbutton panel as shown below.
- **2.** Become familiar with the concepts of Manual and Automatic Operation.
- **3.** Connect the Simulation to a Rockwell PLC.
- **4.** Edit the PLC program from Lab 1 to create the addition functions outlined in the Specifications (this will include expanding the Input and Outputs).
- **5.** Design while keeping in mind that there will be more future additions to equipment and functionality for Lab 3.



Required:

Deliverables:

- Sketch of your design and create any notes required to implement these changes.
- Successful demonstration of Automatic Operation (can be the same code as used in Lab 1).
- Successful demonstration of the basic Manual Operation
- Successful demonstration of End of Cycle Stop (successful restart is not required).
- Copy of PLC Code AND Factoryio Scene Uploaded to Blackboard

Other Specifications:

- Watch video if needed
- Load Scene from Lab 1 and then save as Lab 2
- Create Manual Function and Position Indication for each available motion.
- Manual Function must take into account the potential of damaging a real machine (for instance, you should not be able to move the Gantry horizontally while in the Lowered Position).
- Add sensors as needed to detect positions on start-up (as a minimum, detect: X-Axis Returned, Z-Axis Raised, Clamp Opened and Positioner Lowered).
- Fully document your code.
- Manual and Auto Mode Buttons must be Lighted Pushbuttons
- Light and Buttons for Manual Operation Must be Separate even though the buttons have the ability to be backlit (suggest changing tag names in the Scene for un-used I/O to "-").
- Conveyor Motor Controls must be Lighted Pushbuttons

Notes:

- You may remove the guarding to make it easy to work with the simulation.
- The sample pushbutton panel replaces the exiting panel
- ** The example panel shown here may not have the correct number of Pushbuttons and Lights ... is it **AN EXAMPLE ONLY**

Future Considerations:

- This will be followed up in subsequent labs so you should keep in mind what it will take to add Cameras for Part Detection and Interlocking to Transfer parts from one Simulation to Another via a PLC to PLC Network Connection.
- Adding Detection to only Assemble Matched Pairs

Assembler Lab 2 - Suggested IO Configuration

SENSORS	3			7	ACTUATORS
		Host: 192.168.1.45			
	Maulas X	DOOL IN A		Maria V	
Advance X PB	Moving X	BOOL IN 1	BOOL_OUT_0	Move X	
Auto PB	Item detected	BOOL IN 2	BOOL OUT 2	Grah	
Base at place	lid at place	BOOL IN 3	BOOL OUT 3	Lide conveyor	
Base clamped	Lid at prace	BOOL IN 4	BOOL OUT 4	Clamp lid	
Bases Pos. Low'd Prox.	Pos. at limit (lids)	BOOL IN 5	BOOL OUT 5	Pos. raise (lids)	
Bases Unclamped Prox.	Base at place	BOOL IN 6	BOOL OUT 6	Bases conveyor	
Clamp Base PB	Base clamped	BOOL IN 7	BOOL OUT 7	Clamp base	
Clamp Lid PB	Pos. at limit (bases)	BOOL_IN_8	BOOL_OUT_8	Pos. raise (bases)	
Cycle Start	Part leaving	BOOL_IN_9	BOOL_OUT_9	Cycle Running Lt.	1
Cycle Stop	Cycle Start	BOOL_IN_10	BOOL_OUT_10	Cycle Stop Request Lt	Auto Mode Lt.
Emergency Stop	Man / Auto Reset	BOOL_IN_11	BOOL_OUT_11	Auto Mode Lt.	Base Clamped Lt.
FACTORY I/O (Paused)	Cycle Stop	BOOL_IN_12	BOOL_OUT_12		Base Pos. Low'd Lt.
FACTORY I/O (Reset)	Emergency Stop	BOOL_IN_13	BOOL_OUT_13	Manual Mode Lt.	Base Pos. Raised Lt.
FACTORY I/O (Running)	Auto PB	BOOL_IN_14	BOOL_OUT_14		Base Unclamped Lt.
FACTORY I/O (Time Scale)	FACTORY I/O (Running)	BOOL_IN_15	BOOL_OUT_15		Bases conveyor
Item detected	Manual PB	BOOL_IN_16	BOOL_OUT_16		Bases Conveyor Running
Lid at place	Start Lid Conveyor	BOOL_IN_17	BOOL_OUT_17	Lids Conveyor Running	Bases emitter
Lid clamped	Stop Lid Conveyor	BOOL_IN_18	BOOL_OUT_18		Clamp base
Lids Pos. Low'd Prox.	Start Base Conveyor	BOOL_IN_19	BOOL_OUT_19	Bases Conveyor Running	Clamp lid
Lids Unclamped Prox.	Stop Base Conveyor	BOOL_IN_20	BOOL_OUT_20		Cycle Running Lt.
Lower Pos. Bases PB	Advance X PB	BOOL_IN_21	BOOL_OUT_21	X - Adv'd Lt	Cycle Stop Request Lt
Lower Pos. Lids PB	Return X PB	BOOL_IN_22	BOOL_OUT_22	X - Ret'd Lt.	Digital Display 2
Lower Z PB	Raise Z PB	BOOL_IN_23	BOOL_OUT_23	Z - Raised Lt.	FACTORY I/O (Camera Position)
Man / Auto Reset	Lower Z PB	BOOL_IN_24	BOOL_OUT_24	Z - Lowered Lt.	FACTORY I/O (Pause)
Manual PB	Clamp Lid PB	BOOL_IN_25	BOOL_OUT_25	Lid Clamped Lt.	FACTORY I/O (Reset)
Moving X	Unclamp Lid PB	BOOL_IN_26	BOOL_OUT_26	Lid Unclamped Lt.	FACTORY I/O (Run)
Moving Z	Clamp Base PB	BOOL_IN_27	BOOL_OUT_27	Base Clamped Lt.	Grab
Part leaving	Unclamp Base PB	BOOL_IN_28	BOOL_OUT_28	Base Unclamped Lt.	Lid Clamped Lt.
Pos. at limit (bases)	Raise Pos. Lids PB	BOOL_IN_29	BOOL_OUT_29	Lid Pos. Raised Lt.	Lid Pos. Low'd Lt.
Pos. at limit (lids)	Lower Pos. Lids PB	BOOL_IN_30	BOOL_OUT_30	Lid Pos. Low'd Lt.	Lid Pos. Raised Lt.
Raise Pos. Bases PB	Raise Pos. Bases PB	BOOL_IN_31	BOOL_OUT_31	Base Pos. Raised Lt.	Lid Unclamped Lt.
Raise Pos. Lids PB	Lower Pos. Bases PB	BOOL_IN_32	BOOL_OUT_32	Base Pos. Low'd Lt.	Lids conveyor
Raise Z PB	X - Returned Prox.	BOOL_IN_33	BOOL_OUT_33		Lids Conveyor Running
Return X PB	Lids Pos. Low'd Prox.	BOOL_IN_34	BOOL_OUT_34		Lids emitter
Start Base Conveyor	Lids Unclamped Prox.	BOOL_IN_35	BOOL_OUT_35		Manual Mode Lt.
Start Lid Conveyor	Pos. at limit (lids)	BOOL_IN_36	BOOL_OUT_36		Move X
Stop Base Conveyor	Bases Pos. Low'd Prox.	BOOL_IN_37	BOOL_OUT_37		Move Z
Stop Lid Conveyor	Bases Unclamped Prox.	BOOL_IN_38	BOOL_OUT_38		Pos. raise (bases)
Unclamp Base PB	Pos. at limit (bases)	BOOL_IN_39	BOOL_OUT_39		Pos. raise (lids)
Unclamp Lid PB	Z - Raised Prox	BOOL_IN_40	BOOL_OUT_40		Remover 1
X - Returned Prox.		BOOL_IN_41	BOOL_OUT_41		Remover 2
Z - Raised Prox			INT_OUT_0	Digital Display 2	X - Adv'd Lt
					X - Ret'd Lt.
Dowarad hu INGEAD					Z - Lowered Lt.
Powered by INOCAN www.ingeardrivers.com					Z - Raised Lt.
Paul - Flash - Int - Ann					г [↑] ¬ (О) 2
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Report is Due _____